

## Introduction

Due to the increasing availability of computational resources the Engineering and Research community is gradually moving towards using high fidelity Computational Fluid Dynamics (CFD) models for supporting technical design and specialized analysis. In this context, the CFD Toolkit Proteus is used to perform numerical modelling of physical processes pertaining to wave propagation within coastal and offshore environment and to fluid structure interaction.

## Overview

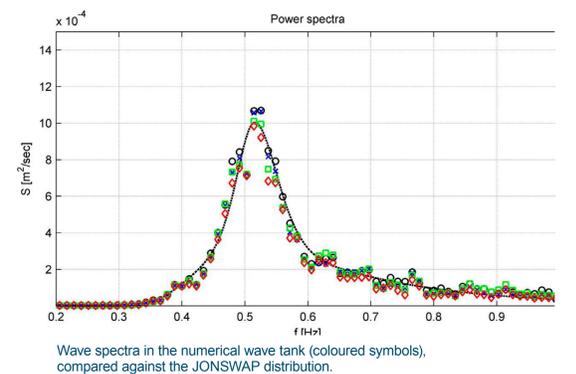
Proteus is a Finite Element Method (FEM) based software originally developed as a computational toolkit for primarily solving generic transport equations. The basic set of the numerical tools is available as an open-source computational methods and simulation toolkit at:  
<https://github.com/erdc-proteus>.

In order to demonstrate the models capabilities in terms of simulating and provide a verification and validation platform for modelling air/water flow cases, a repository containing a customizable set up of numerous benchmarks and test cases is available at <https://github.com/erdc-cm/air-water-vv>.

## Generation of random waves

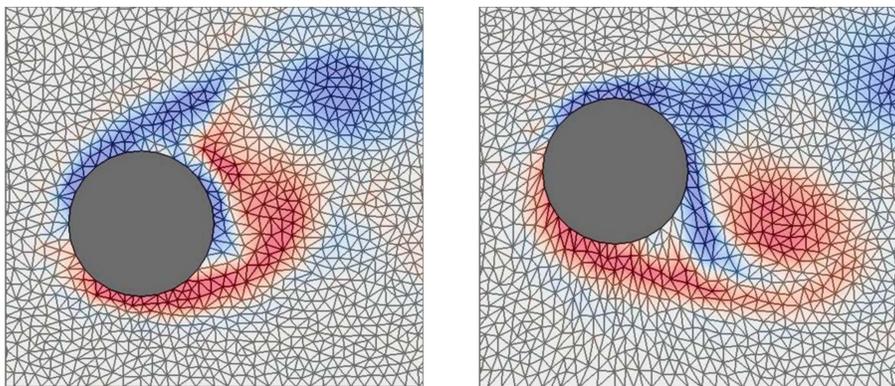
Random waves are of stochastic nature and therefore statistical and spectral properties such as mean and significant wave height, mean and peak period and spectral distribution shape must be defined to describe the wave field. Among the available spectra that can be used to describe a random wave, the most well-known one is the JONSWAP one. A comparison between an analytical JONSWAP spectrum and the numerical results at different locations in the numerical wave tank is shown below.

In Proteus, a novel reconstruction methodology based on signal processing using windows is introduced rather than directly processing the time series of free surface elevation. The method is used for pre-processing a free surface elevation time series and generating the wave field using a reduced number of frequencies. The wave field is introduced in the numerical tank following the relaxation zone method. The method allows reflected waves to be absorbed in both the offshore and the landwards boundary. More details on [1].



## Fluid-structure interaction

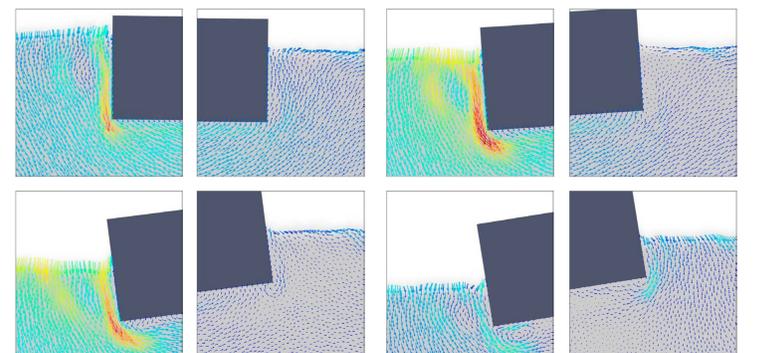
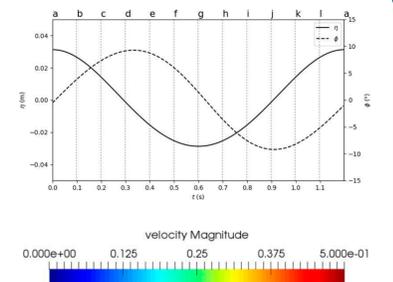
Fluid-Structure Interaction (FSI) is achieved in a partitioned manner, where the multi-body dynamics is computed with the help of another open source tool (Project Chrono [2]). An Arbitrary Lagrangian Eulerian (ALE) technique is used for moving the mesh with the structures, by solving the equation of linear elastostatics in the fluid domain.



Mesh motion for fluid-structure interaction problems.

## Floating structures

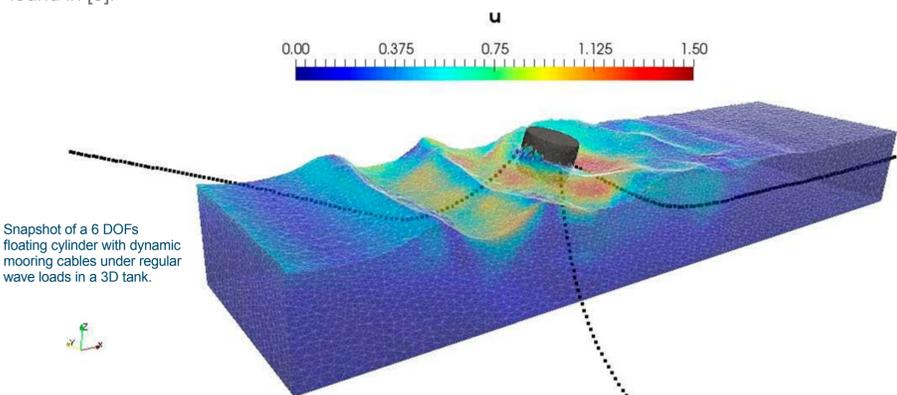
Floating structures require a robust mesh deformation technique as their displacement is usually larger than for coastal defenses under typical conditions. Comparison between experimental results from [3] and numerical results from [4] of a floating body rolling under wave loads show good agreement over the range of frequency tested in terms of Response Amplitude Operator (RAO), capturing nonlinear effects in the fluid (see figure).



Snapshots for roll motion of floating body under wave loads. (a) to (d), showing fluid velocity magnitude and vortices forming around corners.

## Moored structures

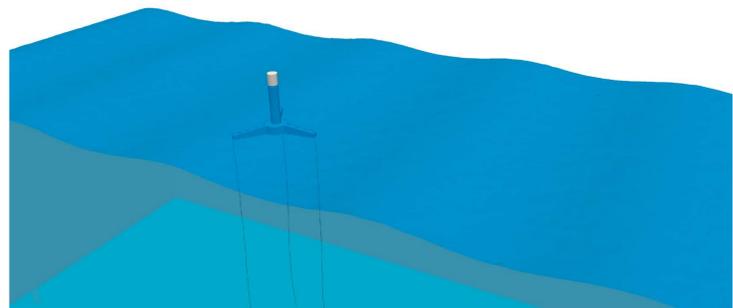
Mooring dynamics can be used to constrain floating structures using FEA with beam theory. The figure shows a snapshot of 6 DOFs cylinder anchored with 3 catenary cables. In these simulations, bending of the cable, as well as drag and added-mass effects on the cable due to the fluid and their effect on the floating structure are taken into account. More details about the implementation can be found in [5].



Snapshot of a 6 DOFs floating cylinder with dynamic mooring cables under regular wave loads in a 3D tank.

## Further work

The aim of the project is to develop robust computational tools for performance assessment of realistic floating structures under extreme environmental conditions. Simulation of a Tension Length Platform (TLP) with associated mooring configuration is currently underway. We will use the toolkit to test various mooring arrangements and look at nonlinear response of mooring lines, associated with extreme loading events.



Snapshot of a 6 DOF TLP cylinder with dynamic mooring (in progress) in a 3D numerical tank.

## References

- [1] Dimakopoulos, A.S., de Lataillade, T. and Kees, C.E., 2019. Fast random wave generation in numerical tanks. Proceedings of the Institution of Civil Engineers-Engineering and Computational Mechanics, pp.1-11.
- [2] Tasora, A., Serban, R., Mazhar, H., Pazouki, A., Melanz, D., Fleischmann, J., Taylor, M., Sugiyama, H. and Negrut, D., 2015, May. Chrono: An open source multi-physics dynamics engine. In International Conference on High Performance Computing in Science and Engineering (pp. 19-49). Springer, Cham.
- [3] Kwang Hyo Jung, Kuang-an Chang, and Hyo Jae Jo. Viscous Effect on the Roll Motion of a Rectangular Structure. Journal of engineering mechanics, 132(2):190-200, 2006.
- [4] Chen, Q., Zang, J., Dimakopoulos, A.S., Kelly, D.M. and Williams, C.J., 2016. A Cartesian cut cell based two-way strong fluid-solid coupling algorithm for 2D floating bodies. Journal of Fluids and Structures, 62, pp.252-271.
- [5] Tristan de Lataillade, Aggelos Dimakopoulos, Christopher Kees, Lars Johanning, David Ingram, and Tezdogan Tezdogan. CFD Modelling coupled with Floating Structures and Mooring Dynamics for Offshore Renewable Energy Devices using the Proteus Simulation Toolkit. In European Wave and Tidal Energy Conference, 2017.

## Acknowledgements

The authors gratefully acknowledge the financial support from ERDC and HR Wallingford through the collaboration agreement (Contract No. W911NF-15-2-0110).

The second author would like to acknowledge support from the IDCORE program from the Energy Technologies Institute and the Research Councils Energy Programme (grant number EP/J500847/).

Permission was granted by the Chief of Engineers to publish this information.